

## **Datasheet**

### **Magnetic Sensor IC**

# **Unipolar Detection High Performance Low Power Hall-Effect Sensor IC**



**AS1914** 

#### General Description

Using low power CMOS process, the AS1914 is designed for low power, high performance unipolar detection hall-effect application, such as cover switch, contactless switch, solid state switch and lid close sensor etc battery operation. The hall IC integrated an on-chip hall voltage generator for magnetic sensing, a comparator that amplifiers the hall voltage, a Chopper amplifier, a Schmitt trigger to provide switching hysteresis for noise rejection, and a complementary output.

The total power consumption of AS1914 is typically less than 3.0uA at 1.8V power supply. AS1914 is designed to respond to alternating South pole. When the magnetic flux density (B) is larger than operate point ( $B_{OPS}$ ), the output will be turned on (low), the output is held until the magnetic flux density (B) is lower than release point ( $B_{RPS}$ ), then turn off (high).

The device is available in DFN1010-4L, DFN1014-4L and SOT553 Packages and is rated over the -40°C to 125°C. The package is RoHS and Green compliant.

#### Features

- Input Voltage Range: 1.65V to 5.0V
- Micro-power consumption ideal for battery power applications
- Unipolar Operation, easy to use as output
- Very high sensitivity hall sensor
- Low Power CMOS process technology
- Chopper stabilization amplifier stage
- Magnetic Sensitivity (typical)
  - ✓ AS1914(S-pole):B<sub>OPS</sub>=30Gauss, B<sub>RPS</sub>=20Gauss
- Good RF noise immunity
- No need pull-up resistor
- Small Solution Size
- RoHS & Green Compliant
- DFN1010-4L, DFN1014-4L and SOT553 Packages
- -40°C to +85 °C Temperature Range

#### Applications

- Cover switch in clam-shell cellular phones
- Cover switch in Notebook, PC/PAD
- Contact-less switch in consumer products
- Solid State Switch
- Handheld Wireless Handset Awake Switch
- Lid close sensor for battery-powered devise
- Magnet proximity sensor for reed switch replacement in low duty cycle applications
- DV, DSC, and White Goods

#### Ordering Information

AS1914XXX

Package: Packing: Temperature Grade:
D: DFN1010-4L R:Tape&Reel N: -40°C~85°C
D2: DFN1014-4L
W: SOT553

Part Number	B <sub>OP</sub> (Gauss)	B <sub>RP</sub> Gauss)	Package Type	Package Qty	Temperature	Eco Plan
AS1914DRN	+30	+20	DFN1010-4L	7-in reel 10000pcs/reel	-40∼85℃	Green
AS1914D2RN	+30	+20	DFN1014-4L	7-in reel 3000pcs/reel	-40∼85℃	Green
AS1914WRN	+30	+20	SOT553	7-in reel 3000pcs/reel	-40∼85℃	Green



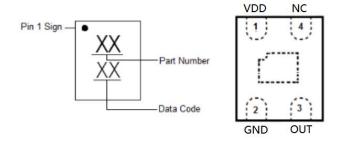
## ■ Marking & Pin Assignment

#### DFN1010-4L



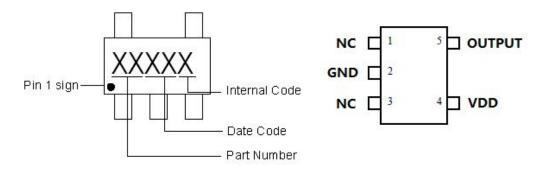
Pin Name	Pin No.	I/O	Pin Function
FIII Name	DFN1010-4L	1/0	FIII FUIICUOII
VDD	2	Р	Input Power Supply
GND	4	Р	Ground
NC	3	-	Not Connected
VOUT	1	0	Output Pin
-	EP	-	Not Connected

#### DFN1014-4L



Pin Name	Pin No.	I/O	Pin Function	
	DFN1014-4L			
VDD	1	Р	Input Power Supply.	
GND	2	Р	Ground.	
OUT	3	0	Output Pin.	
NC	4	-	Not Connected	
-	EP	-	Not Connected	

#### SOT553:



Pin Name	Pin No. SOT553	I/O	Pin Function	
VDD	4	Р	Input Power Supply	
GND	2	Р	Ground	
NC	1, 3	-	Not Connected	
OUTPUT	5	0	Output Pin	



#### ■ Typical Application Circuit

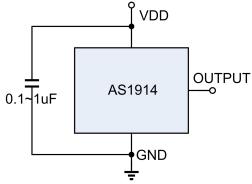


Figure 1, Typical Application Circuit of AS1914

#### ■ Block Diagram

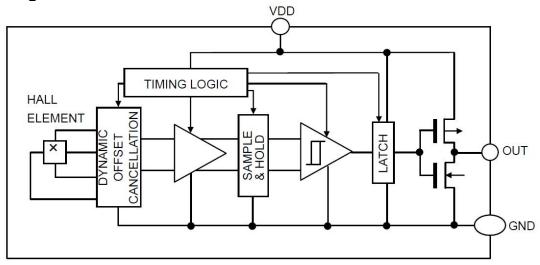


Figure 3, Block Diagram of AS1914

#### ■ **Absolute Maximum Ratings**¹ (T<sub>A</sub>=25°C, unless otherwise noted)

Pa	arameter	Symbol	Rating	Unit
$V_{DD}$	Pin to GND	$V_{DD}$	-0.3 to 5.5	V
Outpu	t Pin to GND	V <sub>OUTPUT</sub>	-0.3 to V <sub>DD</sub> +0.3	V
Max. Continu	ious Output Current	IOUTMAX	1.0	mA
Magneti	ic Flux Density	В	Unlimited	Gauss
Package Power	DFN1010-4L, DFN1216-4L	$P_{D}$	250	mW
Dissipation	SOT553	FD	180	IIIVV
ES	SD (HBM)	ESD	8000	V
Storage Te	mperature Range	Ts	-55 to +150	$^{\circ}$
Operating Juncti	on Temperature Range	T <sub>OP</sub>	-40 to +150	${\mathbb C}$
Maximum Soldering Te	emperature (at leads, 10 sec)	T <sub>LEAD</sub>	300	${\mathbb C}$

#### ■ Recommended Operating Conditions<sup>2</sup>

Parameter	Symbol	Rating	Unit
V <sub>DD</sub> Pin to GND	$V_{DD}$	1.65 to 5.0	V
Continuous Output Current	I <sub>OUT</sub>	1.0	mA
Operating Temperature Range	T <sub>OP</sub>	-40 to +85	$^{\circ}$

Note: 1: Stresses above those listed in absolute maximum ratings may cause permanent damage to the device. Functional operation at conditions other than the operating conditions specified is not implied. Only one absolute maximum rating should be applied at any one time.

<sup>2:</sup> The device is not guaranteed to function outside of its operating conditions.



#### **■** Electrical Characteristics

(T<sub>A</sub> = -40 to +85°C unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C,  $V_{DD}$  = 1.8V)

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
$V_{DD}$	Input Voltage		1.65	-	5.0	V
I(A)(C)	I <sub>DD</sub> (AVG) Average supply current,	T <sub>A</sub> =25℃, V <sub>DD</sub> =1.8V	-	3.0	6.0	
IDD(AVG)	Average supply current,	T <sub>A</sub> = -40°C to 125°C	-	3.0	8.0	μA
T <sub>awake</sub>	Awake Time		-	50	100	μs
T <sub>period</sub>	Period		-	50	100	ms
D.C.	Duty Cycle		-	0.05	-	%
V <sub>OH</sub>	Output Off Voltage (High side)	I <sub>OUT</sub> =+1mA	V <sub>DD</sub> -0.3	V <sub>DD</sub> -0.1	V <sub>DD</sub> +0.3	V
V <sub>OL</sub>	Output On Voltage (Low side)	I <sub>OUT</sub> =-1mA	-0.3	0.1	+0.3	V
Magnetic F	Para. (AS1914)					
Bops	Magnetic Operating Point		-	30	40	Gauss
B <sub>RPS</sub>	Magnetic Release Point		10	20	-	Gauss
B <sub>HYS</sub>	Hysteresis Window		-	10	-	Gauss

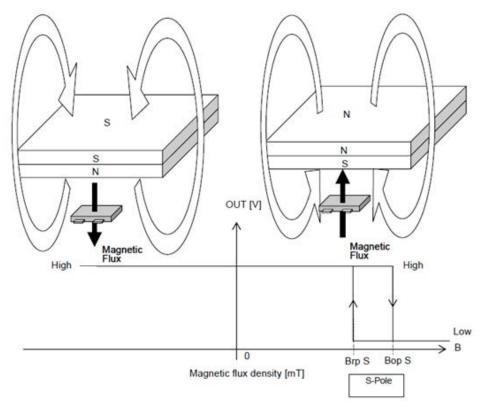
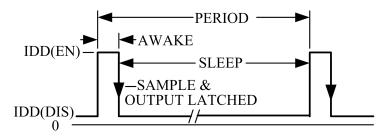


Fig 4, Magnetic Operation Characteristic of AS1914



#### **■** Function Description



#### **Micro-power Operation**

Internal timing circuitry activates the sensor for  $50\mu s$  and deactivates it for the remainder of the period (50ms). A short "awake" time allows for stabilization prior to the sensor sampling and data latching on the falling edge of the timing pulse. The output during the "sleep" time is latched in the last sampled state. The supply current is not affected by the output state.

#### **Chopper-Stabilized Technique**

The Hall element can be considered as a resistor array similar to a Wheatstone bridge. A large portion of the offset is a result of the mismatching of these resistors. These devices use a proprietary dynamic offset cancellation technique, with an internal high-frequency clock to reduce the residual offset voltage of the Hall element that is normally caused by device over-molding, temperature dependencies, and thermal stress. The chopper-stabilizing technique cancels the mismatching of the resistor circuit by changing the direction of the current flowing through the Hall plate using CMOS switches and Hall voltage measurement taps, while maintains the Hall voltage signal that is induced by the external magnetic flux. The signal is then captured by a sample-and-hold circuit and further processed using low-offset bipolar circuitry. This technique produces devices that have an extremely stable quiescent Hall output voltage, are immune to thermal stress, and have precise recoverability after temperature cycling. A relatively high sampling frequency is used for faster signal processing capability can be processed.

#### **Magnetic Field Detection Mechanism**

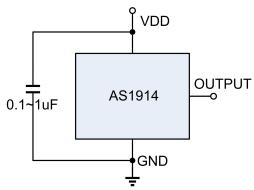
The Hall IC cannot detect magnetic fields that run horizontal to the package top layer. Be certain to configure the Hall IC so that the magnetic field is perpendicular to the top layer.

#### Operation

AS1914 is designed to respond to alternating South pole. When the magnetic flux density (B) is larger than operate point ( $B_{OPS}$ ), the output will be turned on (low), the output is held until the magnetic flux density (B) is lower than release point ( $B_{RPS}$ ), then turn off (high). AS1914 is designed to respond to alternating North pole. When the magnetic flux density (B) is lower than operate point ( $B_{OPN}$ ), the output will be turned on (low), the output is held until the magnetic flux density (B) is larger than release point ( $B_{RPN}$ ), then turn off (high).



#### **Applications:**



AS1914's pole-independent sensing technique allows for operation with south pole magnet orientation, enhancing the manufacturability of the device.

C1 serves two purposes: minimizing ripples on the input voltage and enhancing immunity from RF transmission noises within close proximity. Recommended values are between 10nF and 100nF. The larger the capacitance, the better the noise immunity is for the AS1914.

It is strongly recommended that an external bypass capacitor be connected (in close proximity to the Hall sensor) between the supply and ground of the device to reduce both external noise and noise generated by the chopper-stabilization technique. This is especially true due to the relatively high impedance of battery supplies. The simplest form of magnet that will operate these devices is a bar magnet with south pole near the branded surface of the device.

#### **Thermal Considerations**

The maximum IC junction temperature should be restricted to  $125^{\circ}$ C under normal operating conditions. This restriction limits the power dissipation of the AS1914. Calculate the maximum allowable dissipation,  $P_{D(max)}$ , and keep the actual dissipation less than or equal to  $P_{D(max)}$ . The maximum-power-dissipation limit is determined using following equation:

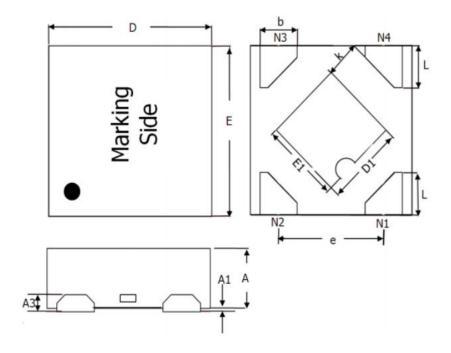
$$P_{D(MAX)} = \frac{125^{\circ}\text{C} - T_A}{R_{\theta JA}}$$

Where,  $T_A$  is the maximum ambient temperature for the application.  $R \in J_A$  is the thermal resistance junction-to-ambient given in Power Dissipation Table.



## ■ Package Information

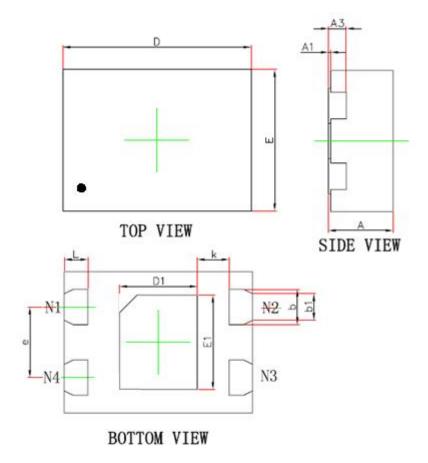
#### DFN1010-4L:



Cumbal	Dimensions In	Millimeters	Dimensions In Inches		
Symbol	Min.	Max.	Min.	Max.	
А	0.340	0.400	0.014	0.016	
A1	0.000	0.050	0.000	0.002	
A3	0.152 E	BSC	0.006	BSC	
D	0.950	1.050	0.038	0.042	
Е	0.950	1.050	0.038	0.042	
D1	0.450	0.550	0.018	0.022	
E1	0.450	0.550	0.018	0.022	
k	0.211 E	BSC	0.008 BSC		
b	0.180	0.280	0.0072	0.0112	
е	0.625 BSC		0.025 BSC		
L	0.200	0.300	0.008	0.012	



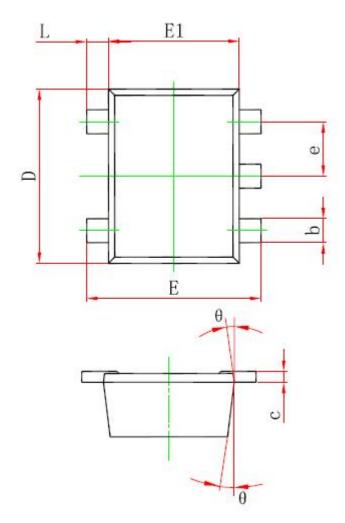
#### DFN1014-4L:

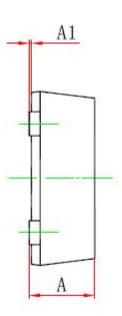


Cumbal	Dimensions In Millimeters			Dim	ensions In I	nches
Symbol	Min.	Nom.	Max.	Min.	Nom.	Max.
А	0. 320	0.370	0.400	0.013	0.014	0.016
A1	0.000	-	0.050	0.000	-	0.002
A3	0.102 (BSC)				0.004 (BSC	;)
D	1.400 (BSC)			0.055 (BSC)		
E	1.000 (BSC)			0.039 (BSC)		
D1	0.500	0.600	0.700	0.020	0.024	0.028
E1	0.700	0.800	0.900	0.028	0.031	0.035
L	0.150	0.200	0.250	0.006	0.008	0.010
b	0.170	0.220	0.270	0.007	0.009	0.011
b1	0.170 0.220 0.270		0.270	0.007	0.009	0.011
е	0.500 (BSC)				0.020 (BSC	;)
k		0.200 (BSC)			0.008 (BSC	;)



#### SOT553:

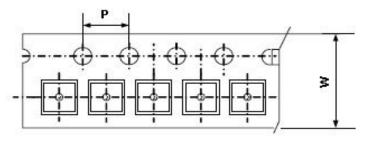


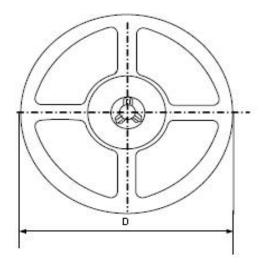


Cymahal	Dimensions Ir	n Millimeters	Dimensions In Inches		
Symbol	Min.	Max.	Min.	Max.	
А	0.525	0.600	0.021	0.024	
A1	0.000	0.050	0.000	0.002	
е	0.450 0.550		0.018	0.022	
С	0.090	0.160	0.004	0.006	
D	1.500	1.700	0.059	0.067	
b	0.170	0.270	0.007	0.011	
E1	1.100	1.300	0.043	0.051	
E	1.500	1.700	0.059	0.067	
θ	7° REF		7° F	REF	
L	0.100	0.300	0.004	0.012	

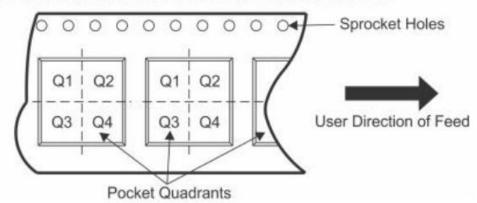


## ■ Packing Information





#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



Package Type	Carrier Width(W)	Pitch(P)	Reel Size(D)	Packing Minimum	Pin 1 Quadrant
DFN1010-4L	8.0±0.1 mm	4.0±0.1 mm	180±1 mm	10000pcs	Q1
DFN1014-4L	8.0±0.1 mm	4.0±0.1 mm	180±1 mm	3000pcs	Q2
SOT553	8.0±0.1 mm	4.0±0.1 mm	180±1 mm	3000pcs	Q3

Note: Carrier Tape Dimension, Reel Size and Packing Minimum